ENGR 34 Course Outline as of Fall 2008

CATALOG INFORMATION

Dept and Nbr: ENGR 34 Title: STATICS
Full Title: Engineering Mechanics: Statics
Last Reviewed: 2/24/2020

Units		Course Hours per Week		Nbr of Weeks	Course Hours Total	
Maximum	3.00	Lecture Scheduled	3.00	17.5	Lecture Scheduled	52.50
Minimum	3.00	Lab Scheduled	0	17.5	Lab Scheduled	0
		Contact DHR	0		Contact DHR	0
		Contact Total	3.00		Contact Total	52.50
		Non-contact DHR	0		Non-contact DHR	0

Total Out of Class Hours: 105.00 Total Student Learning Hours: 157.50

Title 5 Category:	AA Degree Applicable
Grading:	Grade Only
Repeatability:	00 - Two Repeats if Grade was D, F, NC, or NP
Also Listed As:	
Formerly:	

Catalog Description:
A vectorial treatment of the principles of statics with application to engineering problems and an emphasis on common engineering computational tools. Students are required to have a graphing calculator.

Prerequisites/Corequisites:
Course Completion of PHYS 40 (formerly PHYS 4A)

Recommended Preparation:

Limits on Enrollment:

Schedule of Classes Information:
Description: A vectorial treatment of the principles of statics with application to engineering problems and an emphasis on common engineering computational tools. (Grade Only)
Prerequisites/Corequisites: Course Completion of PHYS 40 (formerly PHYS 4A)
Recommended:
Limits on Enrollment:
Transfer Credit: CSU;UC. (CAN ENGR8)

Repeatability: Two Repeats if Grade was D, F, NC, or NP

ARTICULATION, MAJOR, and CERTIFICATION INFORMATION:

AS Degree:	**Area**			Effective:	Inactive:
CSU GE:	**Transfer Area**			Effective:	Inactive:
IGETC:	**Transfer Area**			Effective:	Inactive:
CSU Transfer:	Transferable	Effective:	Fall 1981	Inactive:	
UC Transfer:	Transferable	Effective:	Fall 1981	Inactive:	

CID:

Certificate/Major Applicable:
Major Applicable Course

COURSE CONTENT

Outcomes and Objectives:
Upon completion of the course, students will be able to:
1. Apply a systematic algorithm to the analysis of statics problems.
2. Convert between force and position vectors and between Cartesian and spherical coordinate systems using a scientific calculator.
3. Apply both two and three dimensional vector equations for point equilibrium to solve for the tension or compression in supporting structures.
4. Compute the moment of a force about a point or an axis using cross product, dot product, and mixed triple product.
5. Apply moments and couples to determine equivalent force/moment systems on rigid bodies.
6. Develop vector equations of rigid body equilibrium and solve for the unknown reactions in both two and three dimensions.
7. Analyze trusses, frames, and machines using the principles of Newton's 1st and 3rd laws.
8. Construct shear and bending diagrams given load diagrams to describe the internal forces in beams.
9. Prepare engineering analysis reports with charts, tables, graphics, and proper documentation using spreadsheets.

Optional Objectives:
10. Apply statics principles to the analysis of dry friction statics problems.
11. Apply statics principles to the analysis of hydrostatic pressure problems.
12. Compute the center of mass, centroid, and moment of inertia for areas, volumes, and masses.

Topics and Scope:

1. General Principles
 A. Newton's Laws
 B. Units of Measurement
 C. Numerical Calculations and Homework Standards
 D. Basic Analysis Algorithms
2. Vectors
 A. Vector Addition and Vector Components

B. Force Vectors
C. Position Vectors
D. Dot Product
E. Vector Operations on Scientific Calculators

3. Point Equilibrium
A. Free Body Diagrams
B. Coplanar Force Equilibrium Equations
C. Springs, Pulleys, Maximum-Minimum Relationships
D. Three Dimensional Equilibrium Problems
E. Solution of Systems on Scientific Calculators
F. Independent Variable Solutions on a Spreadsheet
G. Documentation Standards for Engineering Analysis Reports

4. Force System Resultants
A. Moment of a Force At a Point in Two and Three Dimensions
B. Moment of a Force about an Axis
C. Cross Product and Mixed Triple Product on Scientific Calculators
D. Couples
E. Equivalent Systems
F. Reduction of Equivalent Systems
G. Distributed Load Reduction

5. Equilibrium of a Rigid Body
A. Standard Reaction Constraints in Two and Three Dimensions
B. Free Body Diagrams for Rigid Bodies in Two and Three Dimensions
C. Equilibrium Equations for Rigid Bodies in Two and Three Dimensions
D. Equilibrium Special Cases: Two Force Bodies, Three Force Bodies

6. Analysis of Common Engineering Structures
A. Method of Joints Solutions of Trusses
B. Method of Sections Solutions of Trusses
C. Three Dimensional Space Trusses
D. Frames and Machines

7. Internal Forces
A. Section Method for Determining Internal Forces in Two and Three Dimensions
B. Axial Force and Torque Diagram Construction
C. Shear and Bending Moment Diagram Construction

Optional Topics:

8. Friction
A. Characteristics of Dry Friction
B. Wedge Friction Problems
C. Lead Screw Friction Problems
D. Belt Friction Problems
E. Bearing Friction Problems
F. Rolling Resistance Problems

9. Centroids and Center of Mass
A. Centroids of Areas and Volumes using Integration and Composite Body Approach
B. Center of Mass for a System of Particles.
C. Center of Mass of a Body using Integration and Composite Body Approach
D. Theorems of Pappus and Guldinus
E. Hydrostatic Pressure Systems and Their Reduction

10. Moments of Inertia
A. Moments of Inertia for Areas
B. Parallel Axis Theorem
C. Integration and Composite Body Approaches

D. Moments of Inertia for Masses

Assignment:

1. Homework: Approximately 100 problems per semester
2. Group Assignments: 0-2 (depends on instructor)
3. Quizzes, 0-10 (depends on instructor)
4. Midterm exams: no less than two, focused on solving problems
5. Project: 0-1 (depends on instructor)
6. Final exam focused on solving problems

Methods of Evaluation/Basis of Grade:

Writing: Assessment tools that demonstrate writing skills and/or require students to select, organize and explain ideas in writing.

None, This is a degree applicable course but assessment tools based on writing are not included because problem solving assessments are more appropriate for this course.	Writing 0 - 0%

Problem Solving: Assessment tools, other than exams, that demonstrate competence in computational or non-computational problem solving skills.

Homework problems, quizzes	Problem solving 10 - 20%

Skill Demonstrations: All skill-based and physical demonstrations used for assessment purposes including skill performance exams.

None	Skill Demonstrations 0 - 0%

Exams: All forms of formal testing, other than skill performance exams.

Midterms, Final	Exams 65 - 90%

Other: Includes any assessment tools that do not logically fit into the above categories.

Project, Group Assignments	Other Category 0 - 15%

Representative Textbooks and Materials:
Hibbeler, Engineering Mechanics Statics,11th Ed., Prentice Hall, 2007
Meriam, Engineering Mechanics, Statics, 6th Ed., Wiley, 2007